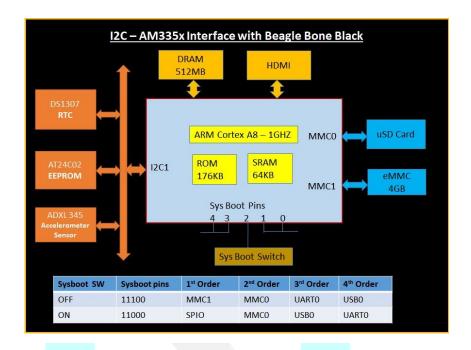


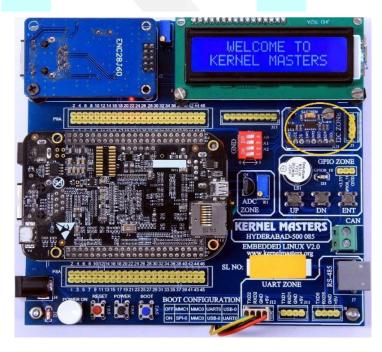
Online/Offline Training on

Linux I2C Drivers

[Master, Slave & User space Drivers]

Add I2C Slave Device with AM3358 Controller
By Kishore Kumar Boddu





Level 2: Linux I2C Drivers

All Sessions are highly interactive hands-on-sessions.

Prerequisites:

- Assumption zero knowledge in I2C Communication Protocol.
- We assume that attendees are fully fluent in C, data structures and that the Linux/Unix command line is a familiar environment.
- Linux System Programming & Device Drivers.
- Embedded Linux Porting knowledge.

Hardware used

- The practical exercises will be run on a Beagle Bone Black (BBB) with a Cortex ARM.
- All exercises will be applicable to any other type of board supported by Linux.
- Online practical demonstration for I2C Master, Slave and User space Drivers on BBB. Later on you can buy and practise, support will be provided. Material will be provided with step by step procedure for lab guidance.
- Device Example: RTC, EEPROM & Accelerometer Sensor

Linux I2C Drivers Syllabus Summary: (Detailed agenda next page)

Session 1: I2C High Level Analysis **Session 2:** I2C Low Level Analysis

Session 3: Developing I2C Master & Slave Drivers in u-boot Space

Session 4: Developing I2C Master & Slave Drivers in Kernel Space **Session 5:** Developing I2C Master & Slave Drivers in User Space

Session 6: Understanding the complete flow

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Level 2: Linux I2C Drivers

All Sessions are highly interactive hands-on-sessions with KM-BBB.

Linux I2C Drivers Detailed Syllabus: Master, Slave & User Space Drivers

Session 1: I2C High Level Analysis

- I2C communication protocol basics/terminology
 - I2C Modes
 - I2C Communication Protocol Format
 - Bus arbitration loss
 - Clock Stretch
- AM3358 Controller (master) I2C specifications & Block Diagram
- ADXL345 & DS1307 (Slave) specifications

Session 2: I2C Low Level Analysis

- Understanding I2C Registers for AM3358 Controller.
- Understanding Accelerometer Sensor [ADXI345] & RTC [DS1307] Specifications, comm.
 Protocol format and register programming model.
- Master Slave interface Block Diagram.

Session 3: Developing I2C Master & Slave Drivers in u-boot Space

U-boot Level

- Add I2C Mux/Pad Configuration in board specific mux file.
- Scan I2C Slave device using I2C command in prompt.
- Test basic communication with slave device using I2C command in u-boot command prompt.

Session 4: Developing I2C Master & Slave Drivers in Kernel Space

Kernel Level

- Add I2C Master/Slave driver platform data in to Device tree source code
- Integrating platform (I2C Master) driver and slave driver with framework.
- Check Probe and initialization functions both Master and slave drivers.
- Registering I2C master/adapter and slave drivers

Session 5: Developing I2C Master & Slave Drivers in User Space

User Level

- Disable I2C Slave driver and test I2C Master Driver with User space driver (i2c-dev) absent of I2C Slave driver.
- Enable I2C Slave driver and test I2C slave driver with device specific applications.

Session 6: Understanding the complete flow

- Understanding I2C Master, slave initialization and device operation source code flow from bottom to top vice versa.
- Understanding I2C Interrupt flow with I2C Debug options.