

# **Embedded Linux Device Driver Development**

# **Yocto Project**

[With ARM Cortex A8]



By Kishore Kumar Boddu

Poky
Build System

Custom build
for BBB

Yocto

Building
BSP Layer

Yocto
Development



#### Who should attend?

- Engineers who are migrating to a yocto Project based distribution environment
- Project managers and engineers who are evaluating the use of Linux for their projects
- Project managers and engineers who are considering supporting their own Linux distribution and tools.

# **Hardware used**

- The practical exercises will be run on a Beagle Bone Black (BBB) with a Cortex ARM.
- All exercises will be applicable to any other type of board supported by Linux.
- Kernel Masters Designed Beagle bone expansion board. For purchase this board contact Kernel Masters Team.

# **Prerequisites:**

- Delegates must have attended Developing with Embedded Linux or an equivalent course, or have some experience of using Linux for Embedded Systems.
- We assume that attendees are fully fluent in C, data structures and that the Linux/Unix command line is a familiar environment.
- Linux System Programming & Device Drivers.
- Embedded Linux Porting knowledge.

# **Course Material:**

https://github.com/kernelmasters



#### **Level 2: Linux I2C Drivers**

# Yocto with Beaglebone Black Summary: (Detailed agenda below)

Part 1: Introduction

Part 2: Yocto Project Overview and Concepts

Part 3: Yocto Project Customization Part 4: Yocto Build – lab Sessions

# **Yocto with Beaglebone Black Detailed Syllabus:**

# **Part 1: Introduction**

#### **Legacy Embedded Linux**

- Embedded Linux Boot sequence
- u-boot customization
- kernel customization
- rootfs customization

**Legacy Embedded Linux vs Yocto Embedded Linux** 

Yocto versions vs Linux kernel versions vs u-boot versions

**Yocto Project Documentation** 

# Part 2: Yocto Project Overview and Concepts

# **Session 1: Introducing the Yocto Project**

- 1.1. What is the Yocto Project?
  - 1.1.1. Features
  - 1.1.2. Challenges
- 1.2. Why Yocto?
- 1.3. Yocto Project Source tree
- 1.4. The Yocto Project Layer Model
- 1.5. Components and Tools
- 1.6. Development Tools
- 1.7. Production Tools
- 1.8. Open-Embedded Build System Components
- 1.9. Reference Distribution (Poky)
- 1.10. Development Methods
- 1.11. Reference Embedded Distribution (Poky)
- 1.12. The OpenEmbedded Build System Workflow

#### **Session 2: The Yocto Project Development Environment**

- 2.1. Open Source Philosophy
- 2.2. The Development Host
- 2.3. Yocto Project Source Repositories
- 2.4. Git Workflows and the Yocto Project
- 2.5. Git
- 2.6. Licensing

## **Session 3: Yocto Project Concepts**

- 3.1. Yocto Project Components
  - 3.1.1. BitBake
  - 3.1.2. Recipes
  - 3.1.3. Classes
  - 3.1.4. Configurations
- 3.2. Layers
- 3.3. OpenEmbedded Build System Concepts



#### **Level 2: Linux I2C Drivers**

- 3.3.1. User Configuration
- 3.3.2. Metadata, Machine Configuration, and Policy Configuration
- **3.3.3.** Sources
- 3.3.4. Package Feeds
- 3.3.5. BitBake
- 3.3.6. Images
- 3.3.7. Application Development SDK
- 3.4. Cross-Development Toolchain Generation
- 3.5. Shared State Cache
  - 3.5.1. Overall Architecture
- 3.5.2. Checksums (Signatures)

# **Part 3: Yocto Project Customization**

## **Session 1: Setting Up to Use the Yocto Project**

- 1.1. Creating a Team Development Environment
- 1.2. Preparing the Build Host
- 1.3. Locating Yocto Project Source Files
- 1.4. Cloning and Checking Out Branches

#### **Session 2: Common Tasks**

- 2.1. Understanding and Creating Layers
- 2.2. Writing a New Recipe
- 2.3. Adding a New Machine
- 2.4. Building
- 2.5. Speeding Up a Build
- 2.6. Working With Libraries
- 2.7. Using x32 psABI
- 2.8. Enabling GObject Introspection Support
- 2.9. Optionally Using an External Toolchain
- 2.10. Creating Partitioned Images Using Wic
- 2.11. Flashing Images Using bmaptool
- 2.12. Making Images More Secure
- 2.13. Creating Your Own Distribution
- 2.14. Creating a Custom Template Configuration Directory
- 2.15. Conserving Disk Space During Builds
- 2.16. Working with Packages

# Session 3: Using the Quick EMUlator (QEMU)

- 3.1. Overview
- 3.2. Running QEMU
- 3.3. Switching Between Consoles
- 3.4. Removing the Splash Screen
- 3.7. QEMU CPU Compatibility Under KVM
- 3.8. QEMU Performance
- 3.9. QEMU Command-Line Syntax
- 3.10. rungemu Command-Line Options

#### **Part 4: Lab Sessions**

- 1. Yocto Building image on x86
- 2. Yocto Building image on BeagleBone Black [BBB]
- 3. Yocto Building image on Kernel Masters Beaglebone black expansion Board.



# **Level 2: Linux I2C Drivers**

# All Sessions are highly interactive hands-on-sessions.

Authored and Compiled By: Boddu Kishore Kumar

Email: kishore@kernelmasters.org

Reach us online: www.kernelmasters.org

Contact: 9949062828

